
FFTHomPy Documentation

Release 1.0.3

Jaroslav Vondřejc

Sep 21, 2017

CONTENTS

1	News:	3
2	Links:	5
3	Contents:	7
3.1	Users guide	7
3.1.1	Installation	7
3.1.2	Running the program	7
3.1.3	Definition of input file	7

FFTHomPy is a Python implementation of FFT-based homogenization based on following papers:

- J. Zeman, T. W. J. de Geus, J. Vondřejc, R. H. J. Peerlings, and M. G. D. Geers: A finite element perspective on non-linear FFT-based micromechanical simulations. 111 (10), pp. 903-926, 2017. arXiv:1601.05970
- N. Mishra, J. Vondřejc, J. Zeman: A comparative study on low-memory iterative solvers for FFT-based homogenization of periodic media, *Journal of Computational Physics*, 321, pp. 151-168, 2016. arXiv:1508.02045
- J. Vondřejc: Improved guaranteed computable bounds on homogenized properties of periodic media by Fourier-Galerkin Method with exact integration, *International Journal for Numerical Methods in Engineering*, 107 (13), pp.~1106-1135, 2016. arXiv:1412.2033
- J. Vondřejc, J. Zeman, I. Marek: Guaranteed upper-lower bounds on homogenized properties by FFT-based Galerkin method, *Comuter methods in Applied Mechanics and Engineering*, 297, pp.~258-291, 2015. arXiv:1404.3614
- J. Vondřejc, J. Zeman, I. Marek: An FFT-based Galerkin method for homogenization of periodic media, *Computers and Mathematics with Applications*, 68, pp. 156-173, 2014. arXiv:1311.0089
- J. Zeman, J. Vondřejc, J. Novák and I. Marek Accelerating a FFT-based solver for numerical homogenization of periodic media by conjugate gradients, *Journal of Computational Physics*, 229 (21), pp.~8065-8071, 2010. arXiv:1004.1122.

License: [MIT](#)

CHAPTER ONE

NEWS:

The software now contains tutorials in folder ‘/tutorial’, which also contains implementation of the method based on exact integration.

CHAPTER TWO

LINKS:

- Source code - git repository: <https://github.com/vondrej/FFTHomPy.git>

CONTENTS:

Users guide

Installation

There is no special installation required. It can be downloaded from <https://github.com/vondrejck/FFTHomPy.git> or using Git by:

```
git clone https://github.com/vondrejck/FFTHomPy.git
```

The code is implemented in `python` and supports versions 2 and 3.

The software also requires the following numerical libraries:

- `numpy`
- `scipy`

Running the program

Command line usage:

```
$ python main.py examples/scalar/scalar_2d.py
```

or only as:

```
$ ./main.py examples/scalar/scalar_2d.py
```

where `examples/scalar/scalar_2d.py` is an input file for *FFTHomPY*.

Definition of input file

Input file for *FFTHomPy* consists of material definition and problem definition.

Material definition

Material coefficients can be defined as matrix-inclusion composites or grid-based composites.

Matrix-inclusions composites

In this case, material is expressed at points \mathbf{x} of periodic cell $\mathcal{Y} = \prod_{i=1}^d (-\frac{Y_i}{2}, \frac{Y_i}{2})$ as

$$\mathbf{A}(\mathbf{x}) = \sum_{i=1}^n f_{(i)}(\mathbf{x} - \mathbf{x}_{(i)}) \mathbf{A}_{(i)}$$

where functions $f_{(i)}$ describe inclusion topologies located at $\mathbf{x}_{(i)}$ with material coefficients $\mathbf{A}_{(i)} \in \mathbb{R}^{d \times d}$. An example of material coefficients is named 'square'

```
import numpy as np

materials = {'square': {'Y': np.ones(dim),
                        'inclusions': ['square', 'otherwise'],
                        'positions': [np.zeros(dim), ''],
                        'params': [0.6*np.ones(dim), ''],
                        'vals': [11*np.eye(dim), 1.*np.eye(dim)]}}
```

and the used keywords have following meanings:

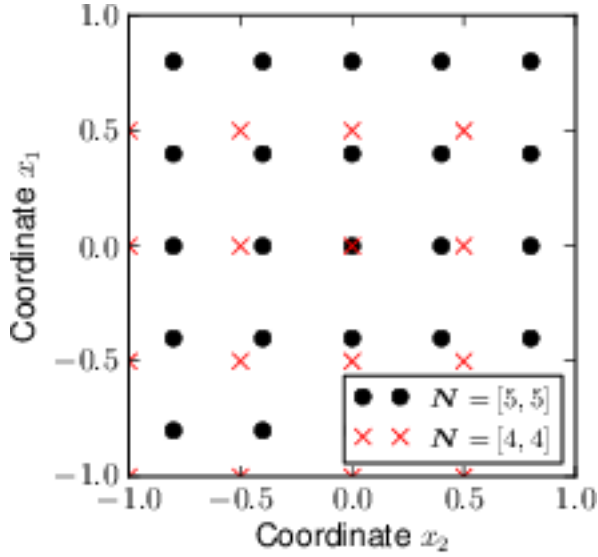
- 'Y': `numpy.array` of shape $(\text{dim},)$ describes the size of periodic cell \mathcal{Y} in dimension dim
- 'inclusions': list of inclusions $f_{(i)}$ of following types
 - 'square', 'circle', and 'otherwise' in two-dimensional settings
 - 'cube', 'ball', and 'otherwise' in two-dimensional settings
- 'positions': list of positions $\mathbf{x}_{(i)}$ corresponding to individual inclusions
 - the position corresponds to center of gravity with respect to coordinate system; the inclusion 'otherwise' has no position because it represents the area in periodic cell omitted by inclusions
- 'params': list of parameters determining the inclusions
 - for 'square' and 'cube', it corresponds to sizes of individual sides
 - for 'circle' and 'ball', it corresponds to diameter
- 'vals': list of material coefficients for individual inclusions; coefficients are represented as `numpy.array` of shape corresponding to physical problem according to problem definition; for scalar elliptic problem, the shape is (dim, dim) while for linearized elasticity the shape is (D, D) where $D = \text{dim} * (\text{dim} + 1) / 2$.

Grid-based composites

Contrary to *Matrix-inclusions composites*, grid-based composites are defined on grid points:

$$\mathbf{x}_{\mathbf{P}}^{\mathbf{k}} = \sum_{\alpha} \frac{Y_{\alpha} k_{\alpha}}{P_{\alpha}} \mathbf{U}^{(\alpha)} \quad \text{for } \mathbf{k} \in \mathbb{Z}_{\mathbf{P}}^d = \left\{ \mathbf{k} \in \mathbb{Z}^d : -\frac{P_{\alpha}}{2} \leq k_{\alpha} < \frac{P_{\alpha}}{2} \right\}$$

for some number of points $\mathbf{P} \in \mathbb{N}^d$ and the size $\mathbf{Y} \in \mathbb{R}^d$ of periodic cell $\mathcal{Y} = \prod_{i=1}^d (-\frac{Y_i}{2}, \frac{Y_i}{2}) \subset \mathbb{R}^d$; examples for odd and even grids are depicted in following figure



for periodic cell $\mathcal{Y} = \prod_{i=1}^d (-1, 1)$ with the cell size $Y = (2, 2)$.

The material is then approximated with the following formula

$$A(x) = \sum_{k \in \mathbb{Z}_P^d} \psi(x - x_P^k) A(x_P^k) \quad \text{for } P \in \mathbb{N}^d \text{ and } x \in \mathcal{Y} \quad (3.1)$$

where function $\psi : \mathcal{Y} \rightarrow \mathbb{R}^d$ is taken either by

$$\text{rect}_h(x) = \begin{cases} 1 & \text{if } |x_\alpha| < \frac{h_\alpha}{2} \text{ for all } \alpha \\ 0 & \text{otherwise} \end{cases} \quad \text{for } h = \left(\frac{Y_\alpha}{P_\alpha} \right)_{\alpha=1}^d \quad (3.2)$$

leading to piece-wise constant approximation of material coefficients, or by

$$\text{tri}_h(x) = \prod_{\alpha} \max\{1 - |\frac{x_\alpha}{h_\alpha}|, 0\} \quad \text{for } h = \left(\frac{Y_\alpha}{P_\alpha} \right)_{\alpha=1}^d \quad (3.3)$$

leading to piece-wise bilinear approximation of material coefficients.

In comparison to *Matrix-inclusions composites*, the material coefficients definition

```
materials.update({'square_Ga': {'Y': np.ones(dim),
                                'inclusions': ['square', 'otherwise'],
                                'positions': [np.zeros(dim), ''],
                                'params': [0.6*np.ones(dim), ''],
                                'vals': [11*np.eye(dim), 1.*np.eye(dim)],
                                'order': 0,
                                'P': 5*np.array(dim)}})
```

contains two additional parameters:

- 'P': numpy.array of shape (dim,) describes the resolution of approximation in (3.1)
- 'order': define approximation order:
 - 0: constant approximation according to (3.2)
 - 1: bilinear approximation according to (3.3).

Problem definition

Here, the example of problem description is stated:

```
problems = [{ 'name': 'probl',
              'physics': 'scalar',
              'material': 'square',
              'solve': { 'kind': 'GaNi',
                        'N': N,
                        'primaldual': ['primal', 'dual'] },
              'postprocess': [{ 'kind': 'GaNi',
                                { 'kind': 'Ga',
                                  'order': None },
                                { 'kind': 'Ga',
                                  'order': 0,
                                  'P': N },
                                { 'kind': 'Ga',
                                  'order': 1,
                                  'P': 27*N } ] },
              'solver': { 'kind': 'CG',
                          'tol': 1e-6,
                          'maxiter': 1e3 } } ]
```

The individual keywords are explained:

- **'name'**: the name of a problem
- **'physics'**: defines the physical problem that is solved; following alternatives are implemented:
 - **'scalar'**: scalar linear elliptic problem (diffusion, stationary heat transfer, or electric conductivity)
 - **'elasticity'**: linearized elasticity (small strain)
- **'material'**: keyword referring to dictionary materials or directly dictionary defining the material coefficients
- **'solve'**: defines the problem discretization, the way how to solve minimizers (corrector functions)
 - **'kind'**: is either **'Ga'** (Galerkin approximation) or **'GaNi'** (Galerkin approximation with numerical integration); it thus corresponds to the discretization way
 - **'N'**: is a `numpy.array` defining the approximation order of trigonometric polynomials; the higher the value is, the better approximation is provided
 - **'primaldual'**: determine if primal, dual, or both formulations are calculated
- **'solver'**: defines the linear solver and relating parameters
 - **'kind'**: linear solver one of **'CG'** for Conjugate gradients, **'BiCG'** for Biconjugate gradients, **'richardson'** for Richardson's iterative solution, **'scipy_cg'** for `scipy.sparse.linalg.cg`, and **'scipy_bicg'** for `scipy.sparse.linalg.bicg`,
 - **'tol'**: the required tolerance (float) for the convergence of linear solver
 - **'maxit'**: the maximal number of iterations
- **'postprocess'**: defines the way for calculating homogenized material coefficients from minimizers that are o
 - **'kind'**: is either **'Ga'** (Galerkin approximation) or **'GaNi'** (Galerkin approximation with numerical integration); it thus corresponds to the discretization way
 - **'order'**: applicable only for **'Ga'**, it defines approximation order according to (3.2) or (3.3)
 - **'P'**: applicable only for **'Ga'**, this `numpy.array` of shape `(dim,)` describes the resolution of approximation in (3.1)